

# Geo-neutrino observation in KamLAND & new detectors

AAP 2024, RWTH Aachen Univ.

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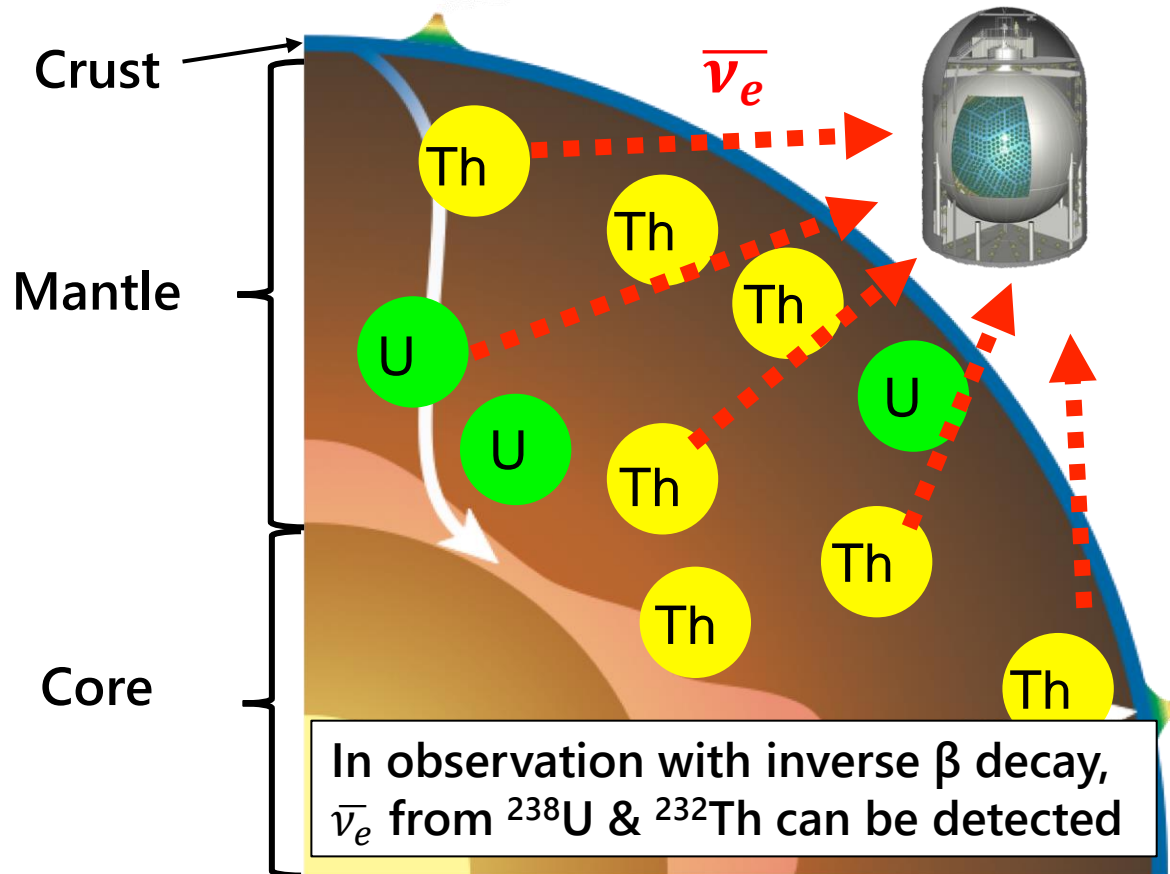
D1 Daiki Morita



# Introduction : Geo-ν overview

- Geo-ν is  $\bar{\nu}_e$  from  $\beta$  decay of isotopes in the Earth, especially  $\bar{\nu}_e$  from  $^{238}\text{U}$  &  $^{232}\text{Th}$ .
- Geo-ν can directly measure the amount of Earth's engine power source.

## Earth's structure & Geo-ν



## Earth's heat

**Primordial heat**  
The residual heat from Earth's formation

+

**Radiogenic heat**  
Energy from radioactive decay

These heat drives

- Mantle convection
- Geomagnetism
- Plate tectonics

However, these ratio and distribution are unknown...

Q : How do we measure ?

→ Geo ν flux is proportional to U & Th

→ **The amount of radiogenic heat can be estimated!**

# Today's outline

- I will talk about status of KamLAND Geo- $\nu$  observation and new detector ideas for more precise measurements.

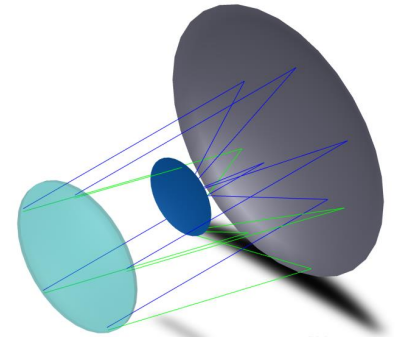
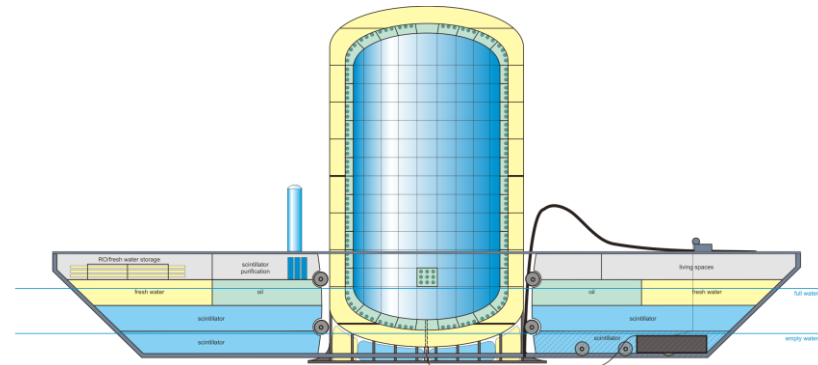
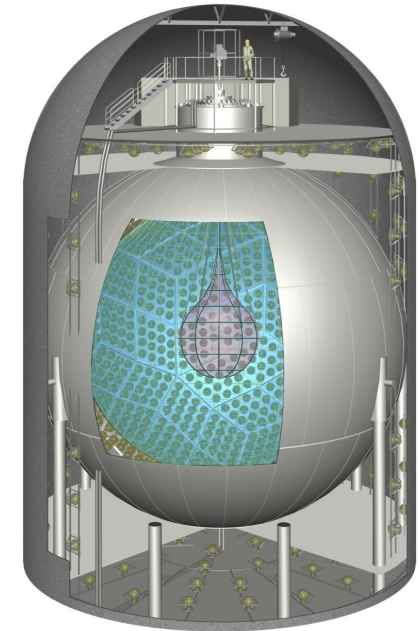
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- Overview
- Latest result
- Near future : Accidental BG reduction with machine learning

### 2. New detectors

- OBD : Ocean bottom detector
- Imaging detector

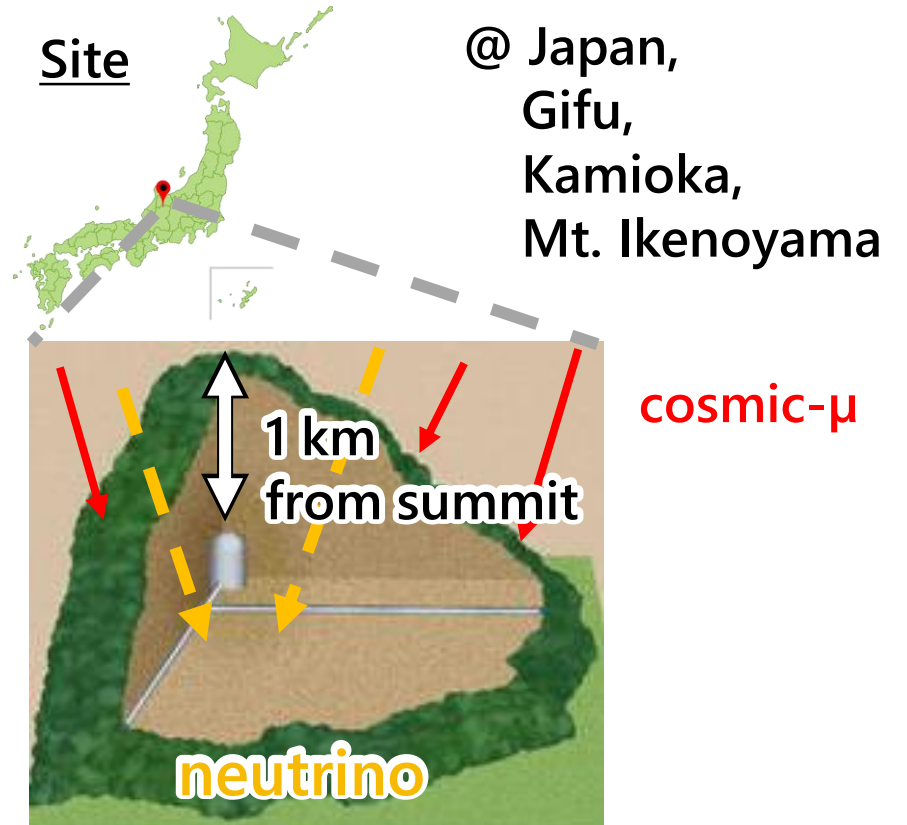
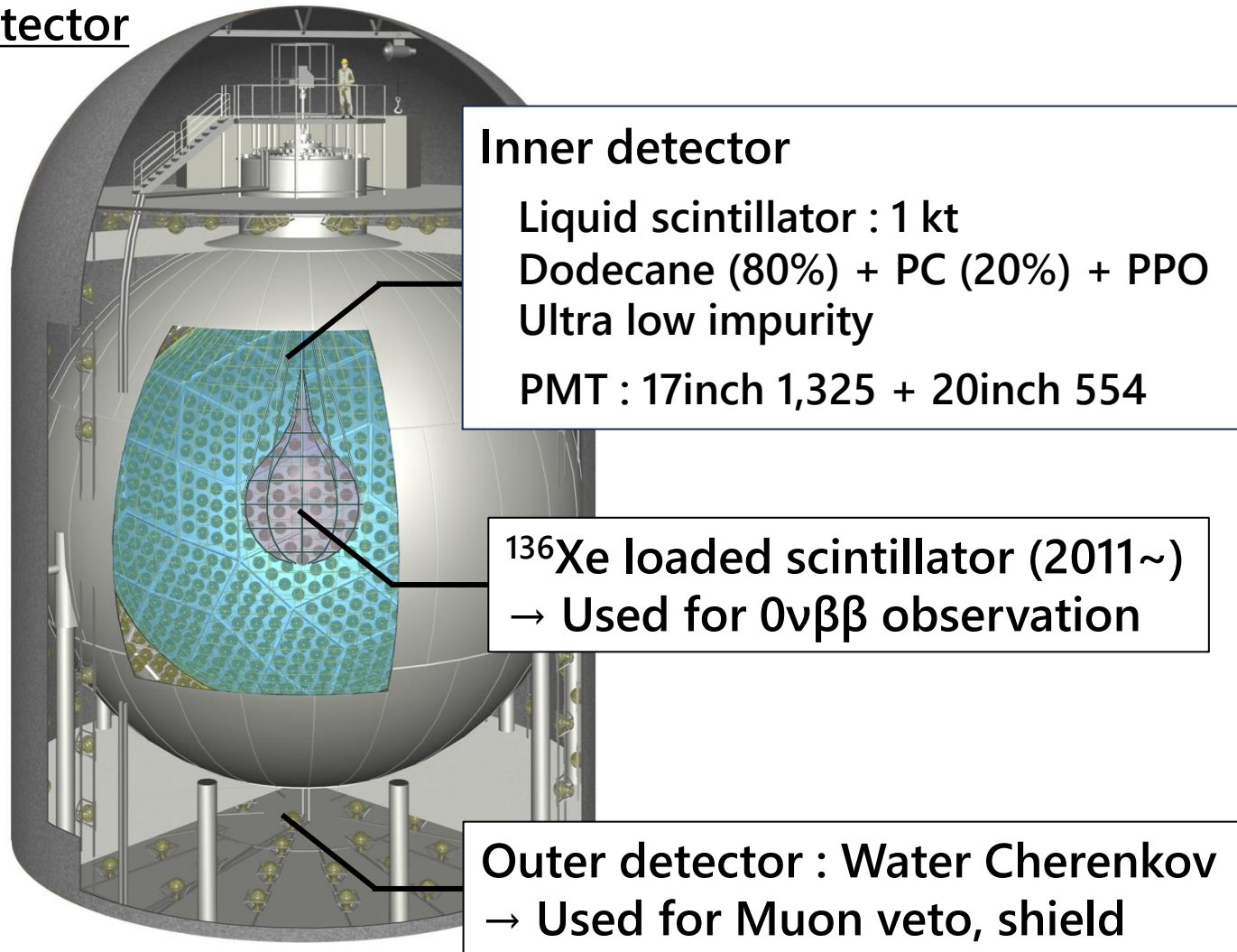


# 1. Geo-neutrino observation in KamLAND

# KamLAND Kamioka Liquid Anti-Neutrino Detector

- Large liquid scintillator detector in ultra-low radioactivity environment

## Detector



## Status

DAQ has been completed in this August !!

# How to observe $\bar{\nu}_e$ & Background events

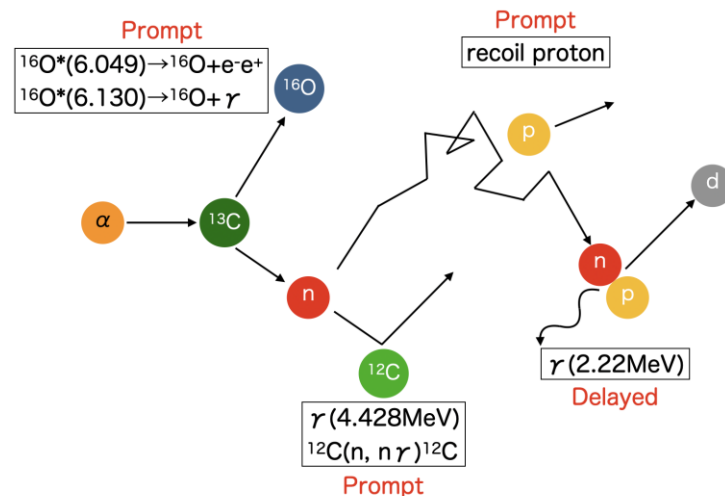
- KamLAND observes  $\bar{\nu}_e$  by delayed coincidence (DC).
- Reactor  $\nu$ ,  $^{13}\text{C}(\alpha, n)^{16}\text{O}$ , Spallation, Accidental are main background of Geo- $\nu$  observation.

## Background of Geo $\nu$ observation (Representative)



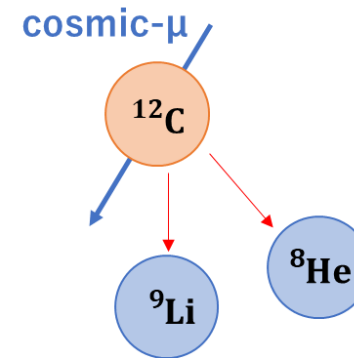
Reactor  $\nu$

$\bar{\nu}_e$  from reactor



$^{13}\text{C}(\alpha, n)^{16}\text{O}$

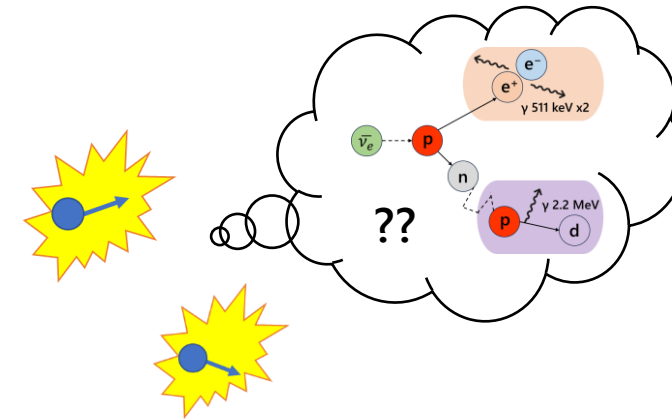
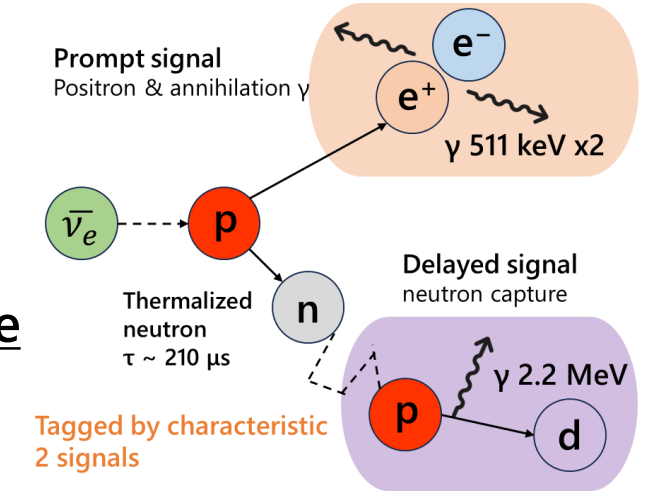
Series of reactions triggered by  $\alpha$  decay of radioactive impurities



Spallation from  $^{12}\text{C}$

$\beta^- + n$  reaction by nuclei produced from crushed  $^{12}\text{C}$

## Delayed coincidence



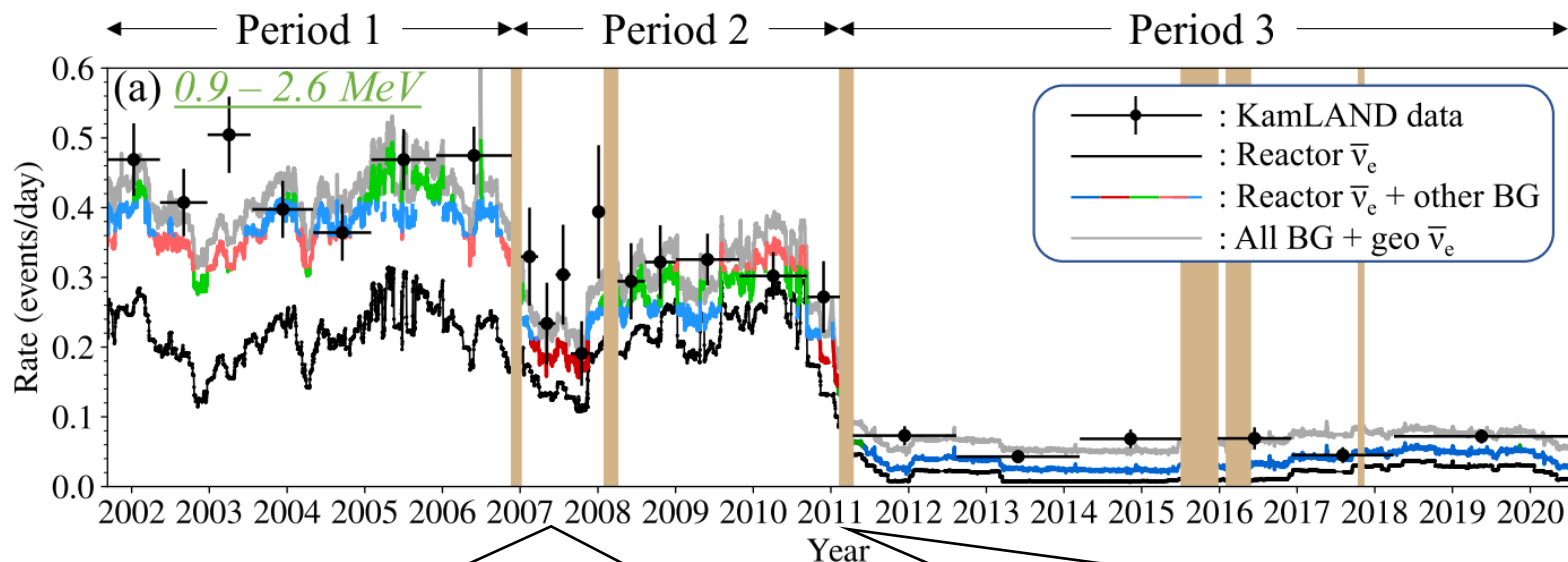
Accidental

Not inverse  $\beta$  decay event, but two events which meets delayed coincidence selection

# Latest result : Energy spectrum & Event rate trend

- KamLAND achieved Geo- $\nu$  observation with low BG.

## Event rate trend

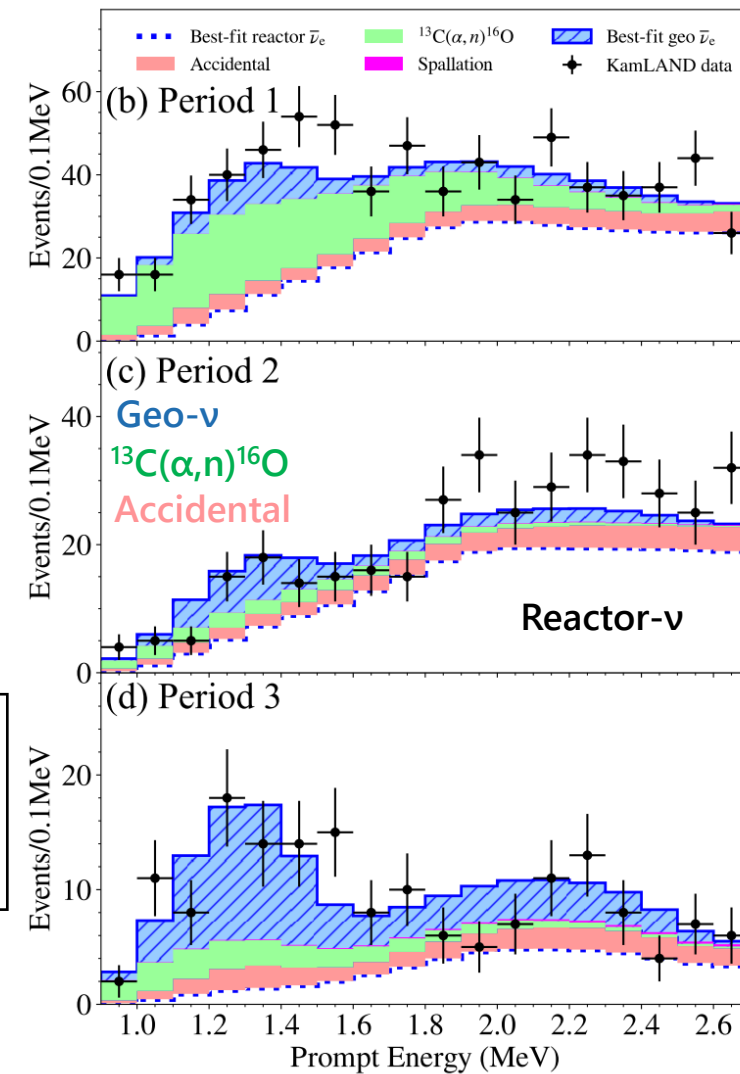


Liquid scintillator distillation  
→ Reducing radioactive impurity

Huge earthquake occurred in Japan  
→ stopped Most of Japan reactors  
→ Reactor  $\nu$  was decreased

Dataset : Mar, 2002-Dec, 2020  
Livetime : 5,227 days  
(low-reactor phase : 2,590 days)

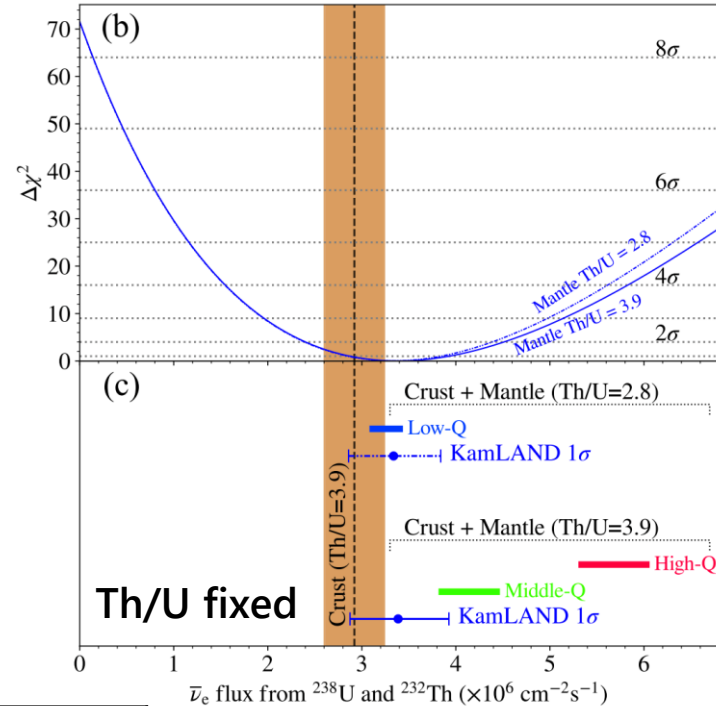
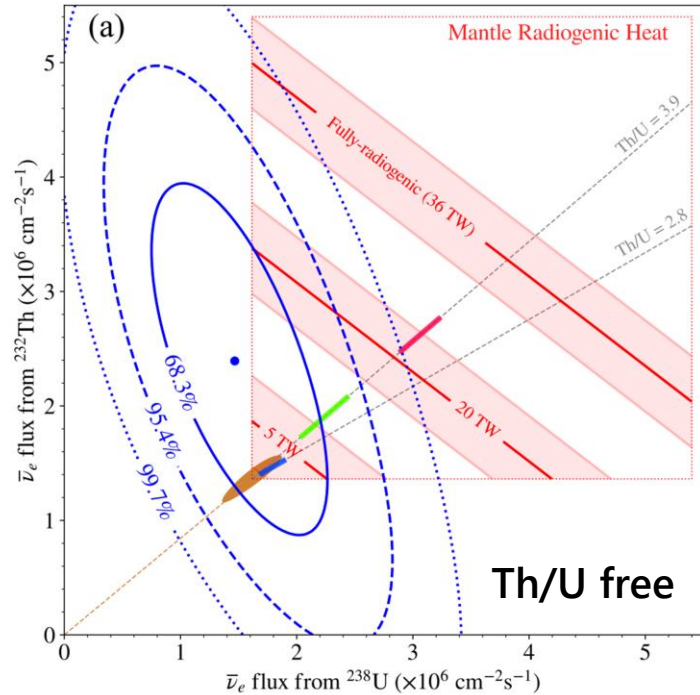
## Energy spectrum (best fit)



# Latest result : Neutrino flux from $^{238}\text{U}$ & $^{232}\text{Th}$

## - KamLAND constrained heat contribution from U & Th.

### Best fit for $^{238}\text{U}$ & $^{232}\text{Th}$ Geo-v flux



	N of event	0 signal rejection
U	$117^{+41}_{-39}$	$3.3\sigma$
Th	$58^{+25}_{-24}$	$2.4\sigma$
U+Th	$174^{+31}_{-29}$	$8.3\sigma$

**High-Q (Rich-H) rejected at 99.76 % C.L.**  
(homogeneous mantle)  
**97.9% C.L. (concentrated at CMB)**

### Radiogenic heat calculation

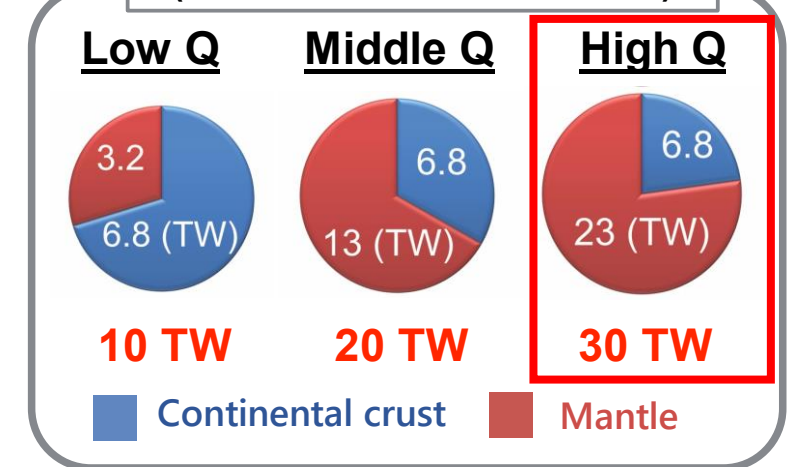
Adding heat estimate from crust  
 $^{238}\text{U}$  : 3.35 TW     $^{232}\text{Th}$  : 3.61 TW

$$Q^{\text{U}} = 3.3^{+3.2}_{-0.8} \text{ TW}$$

$$Q^{\text{Th}} = 12.1^{+8.3}_{-8.6} \text{ TW}$$

$$Q^{\text{U}} + Q^{\text{Th}} = 15.4^{+8.3}_{-7.9} \text{ TW}$$

### Total radiogenic heat prediction (Continental Crust + Mantle)



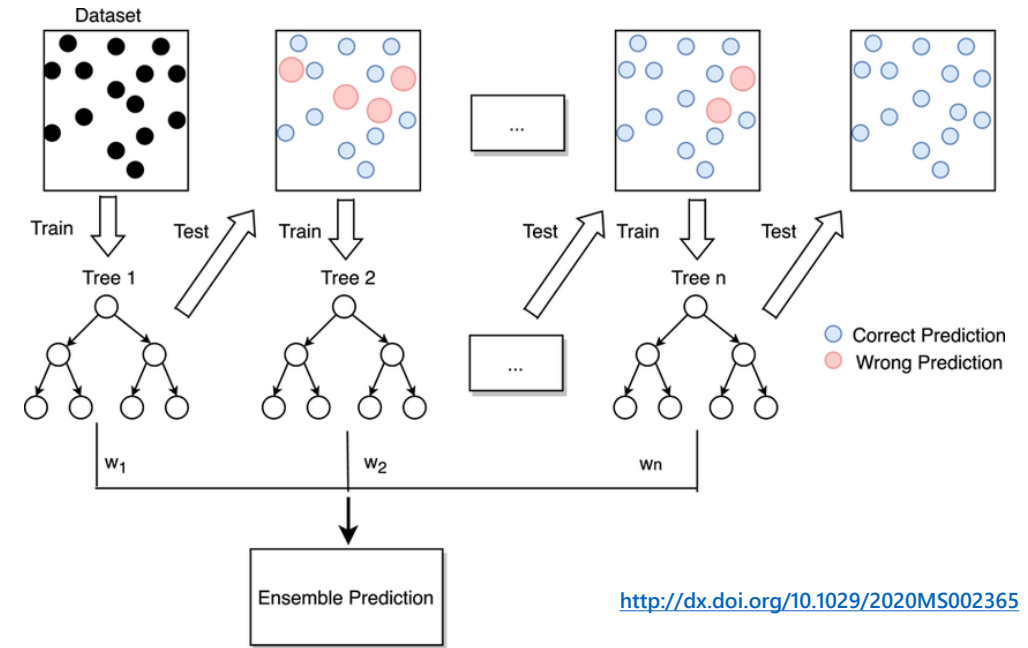


# Near future : BG reduction with machine learning

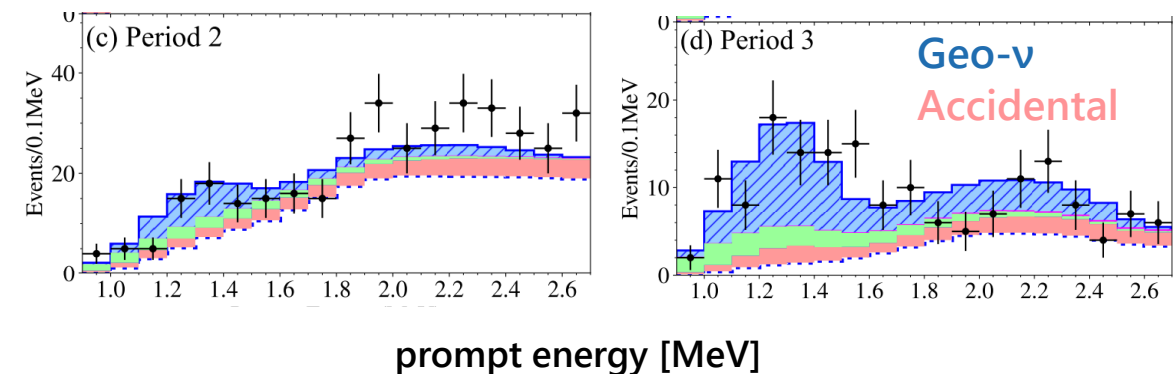
- Gradient boosting decision tree is powerful algorithm for BG reduction.

## GBDT: Gradient Boosting Decision Tree

- Machine learning model using
  - Decision tree  
Model that breaks down data into hierarchically smaller subset based on the data's features  
It becomes tree like structure
  - Boosting  
Creating weak learner (e.g. decision tree) iteratively to correct the errors in previous learning result
  - Gradient descent  
Optimization algorithm used to minimize a function  
In GBDT, iteratively adding correction value to prediction
- Can be used for regression, classification  
→ being applied to accidental BG reduction



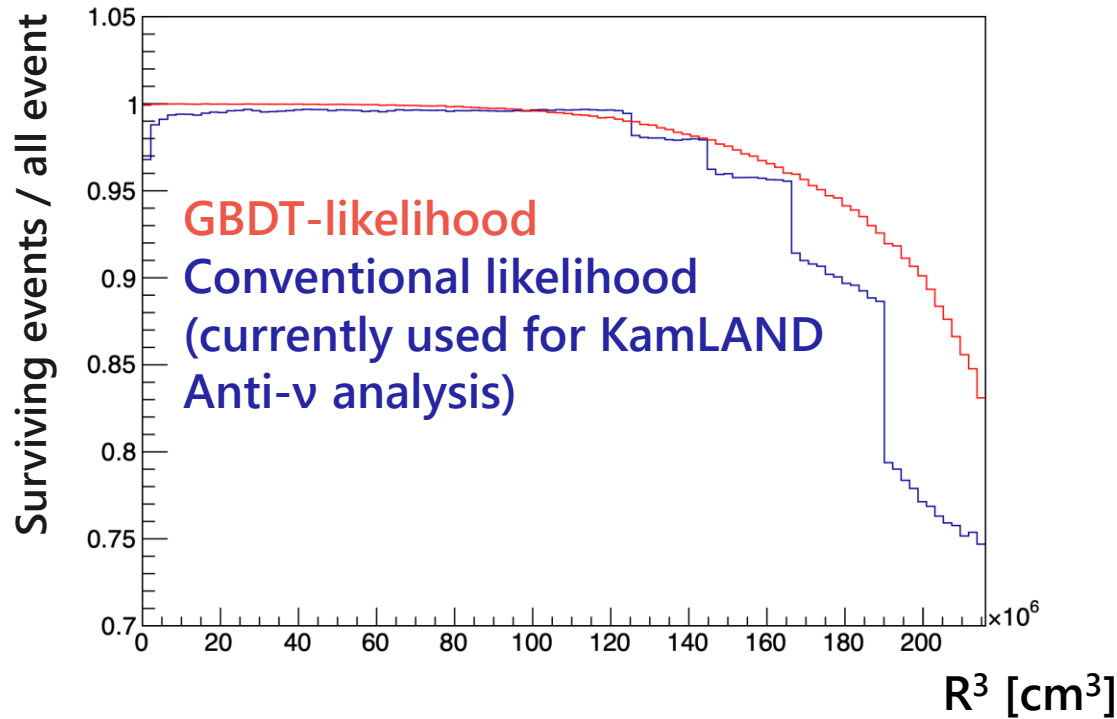
<http://dx.doi.org/10.1029/2020MS002365>



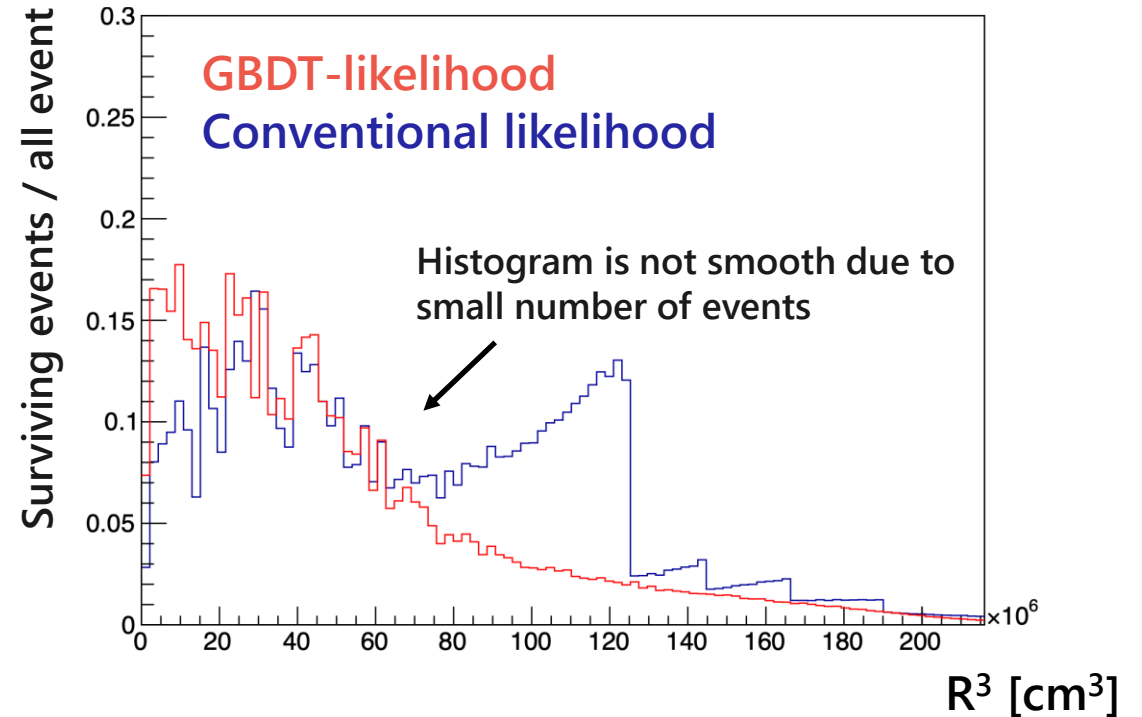
# Accidental background identification with GBDT

- GBDT remarks higher reduction efficiency than conventional likelihood.

## Anti-neutrino signal (MC)



## Accidental background (off-time delayed coincidence)



GBDT-likelihood using  $(E_p, X_p, Y_p, Z_p, E_d, X_d, Y_d, Z_d, \Delta R, \Delta T)$   
conventional likelihood PDF using  $(E_p, E_d, \Delta R, \Delta T, R_p, R_d)$

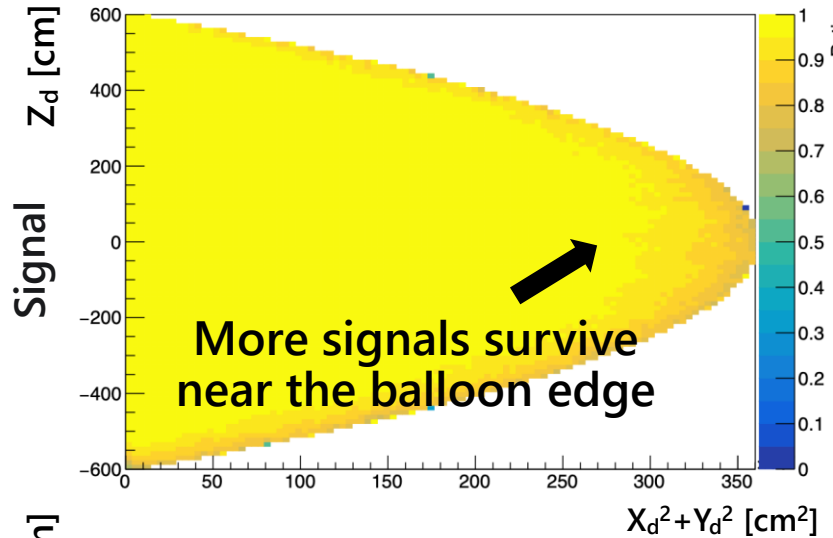
When GBDT use, Accidental : 40 % decrease  
Signal : 8 % increase

# Accidental background identification with GBDT

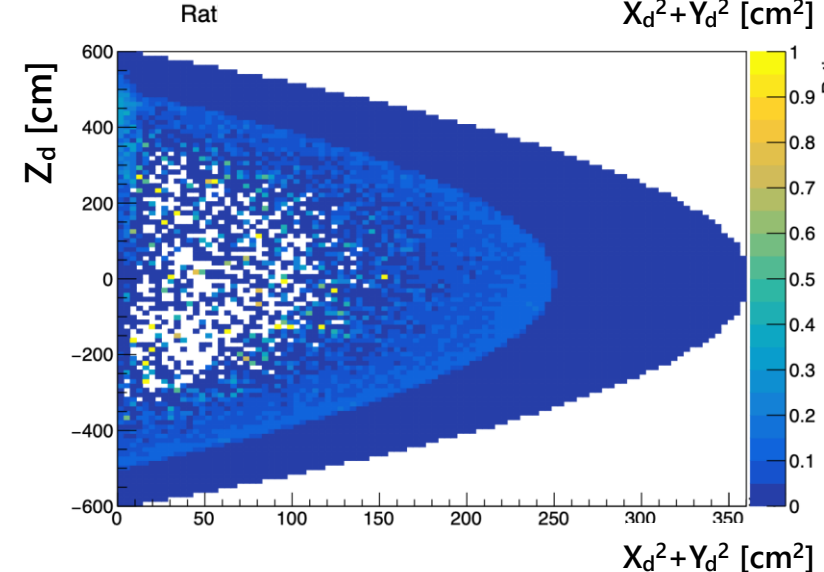
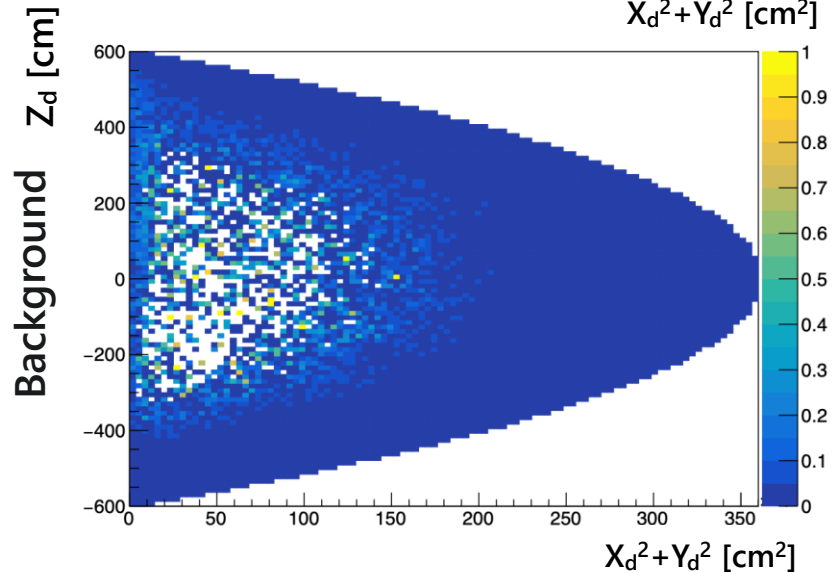
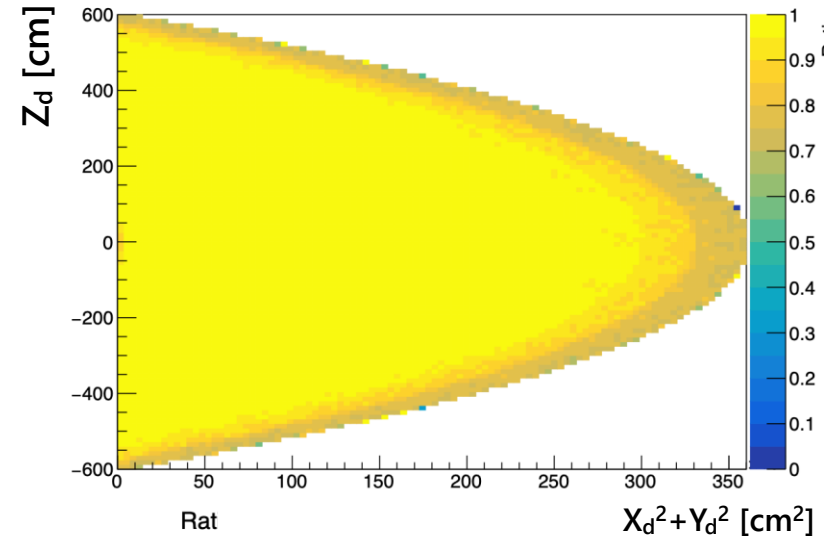
Distribution of remaining ratio in KamLAND

$\frac{Z \text{ axis Surviving events}}{\text{All event}}$

GBDT-likelihood



Conventional likelihood



GBDT improves sensitivity ! → KamLAND full data analysis with GBDT is ongoing !

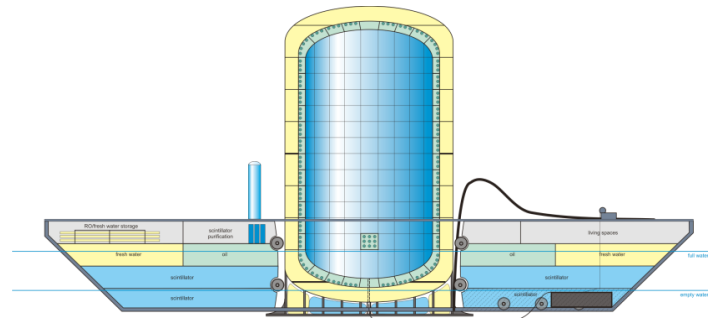
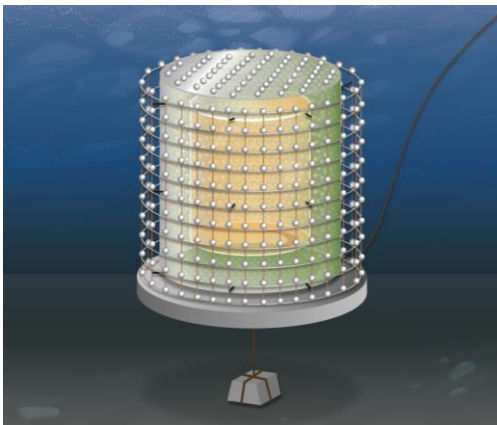
## 2. New detector

# Challenge for more precise Geo- $\nu$ observation

- Large uncertainty of  $\nu$  from crust
  - Geo- $\nu$  comes from mantle & crust.
  - Uncertainty of crustal flux model is larger than that of Geo- $\nu$  observation.
    - difficult to obtain insight on the mantle
  - Continental detectors have ~20% contribution from crust



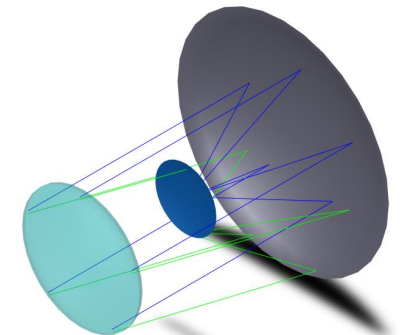
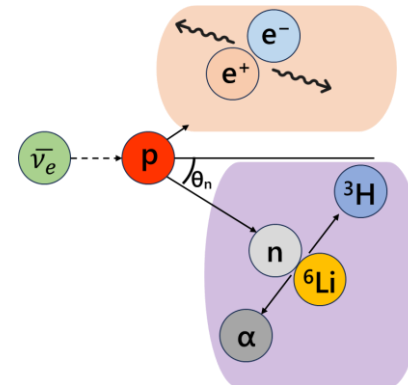
## Ocean bottom detector



- Reactor  $\nu$  identification
  - Reactor  $\nu$  and Geo- $\nu$  make same signal in liquid scintillator.
  - However, arrival direction is different.



## $\bar{\nu}_e$ direction detection with imaging (imaging detector)

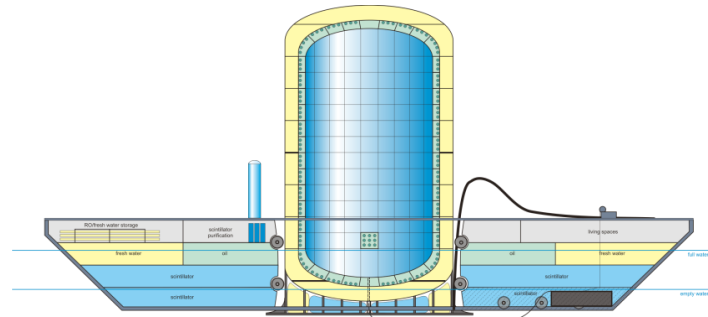
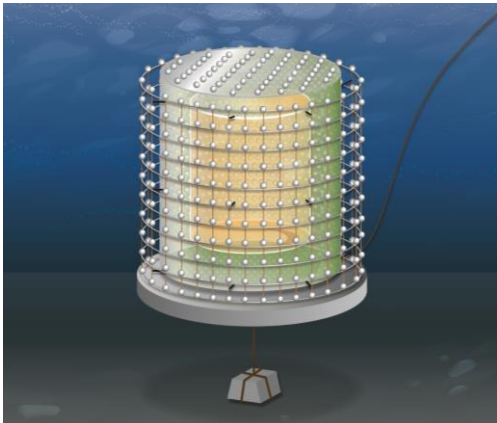


# Challenge for more precise Geo- $\nu$ observation

- Large uncertainty of  $\nu$  from crust
  - Geo- $\nu$  comes from mantle & **crust**.
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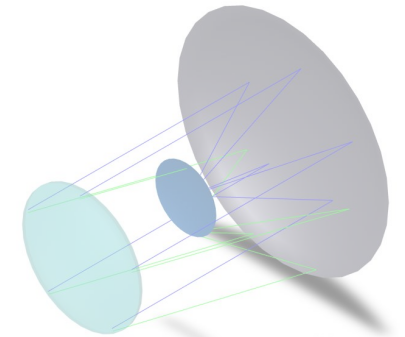
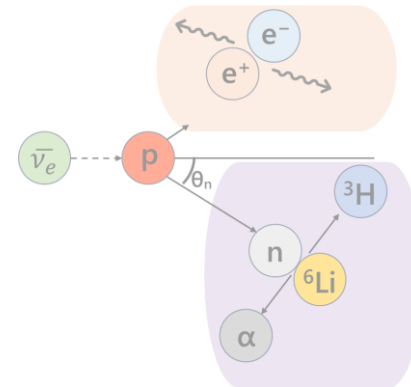
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## $\bar{\nu}_e$ direction detection with imaging (imaging detector)



# OBD Ocean Bottom Detector

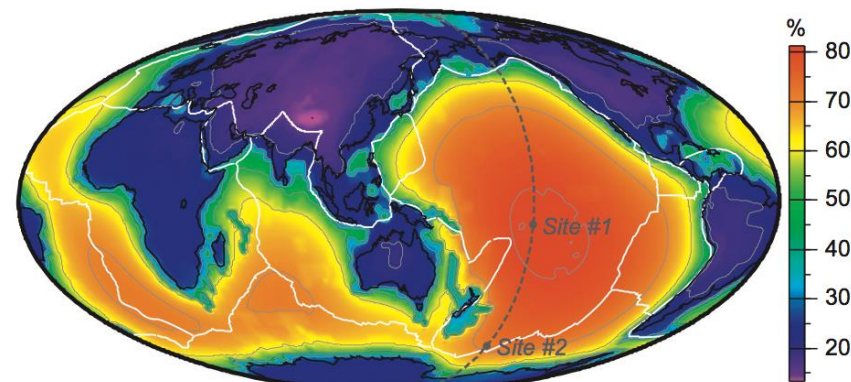
- Liquid scintillator detector in deep sea to observe Mantle Geo- $\nu$

## Merit of Geo- $\nu$ observation in deep sea

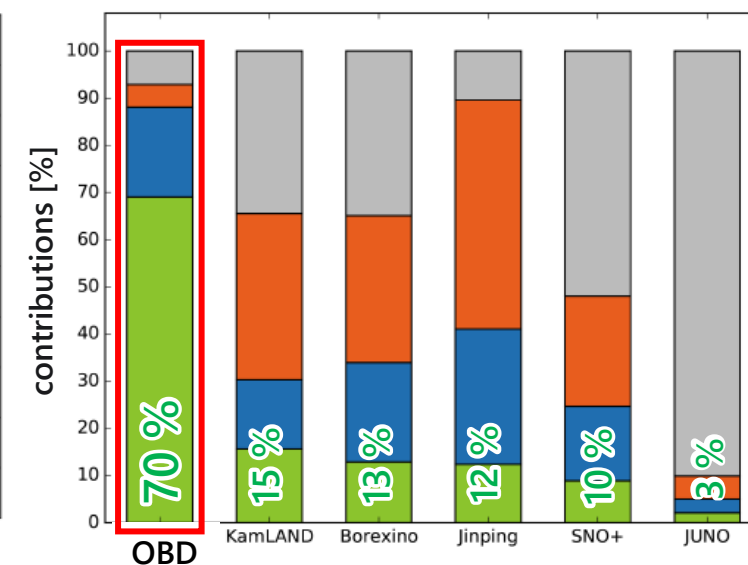
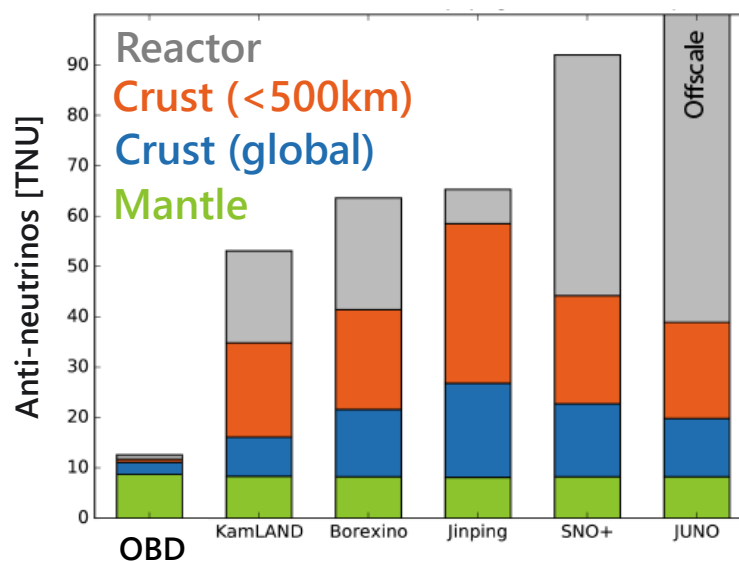
- Oceanic crust is thinner than continental crust
- U & Th in oceanic crust is lower than continental crust
  - Mantle  $\nu$  contribution is greater than in continental observation
- Far away from any reactors
  - Low BG environment

Ocean bottom is suitable site for Mantle  $\nu$  observation.

Ratio of Geo  $\nu$  flux : Mantle/Total



Šrámek et al (2013) EPS, 10.1016/j.epsl.2012.11.001



# R&D of OBD

- Prototype detector is now R&D phase.

## Goal of OBD

- 10 ~ 50 kt of liquid scintillator
- 1 ~ 5 km under the pacific ocean
- Movable

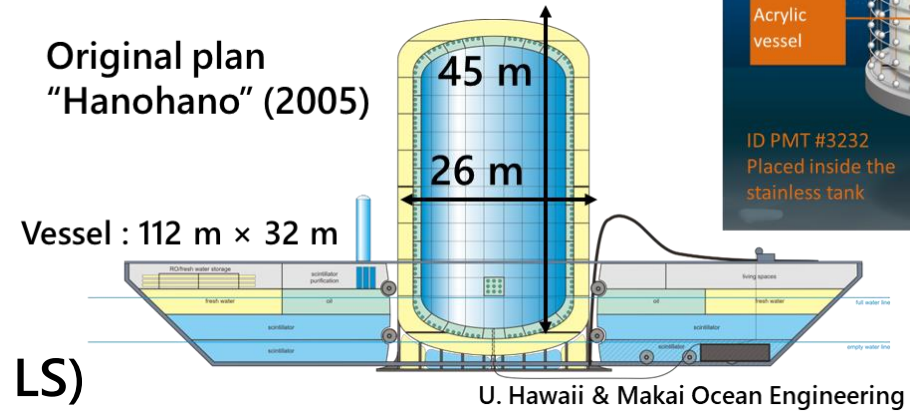
## Current progress

- Researching property of detector component
- Planning to begin prototype detector (~20kg LS) testing in deep sea within 1 year

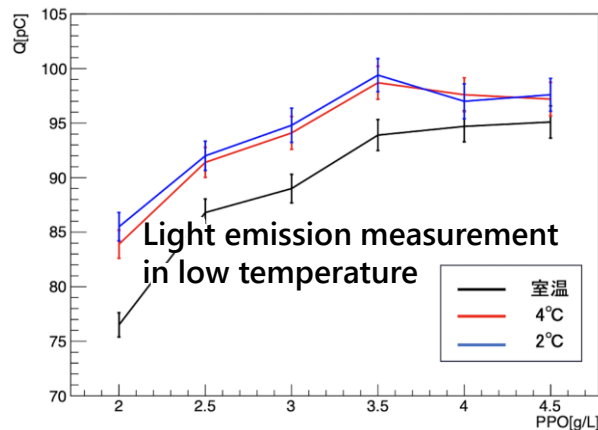
Intermediate target  
1.5 kt design OBD



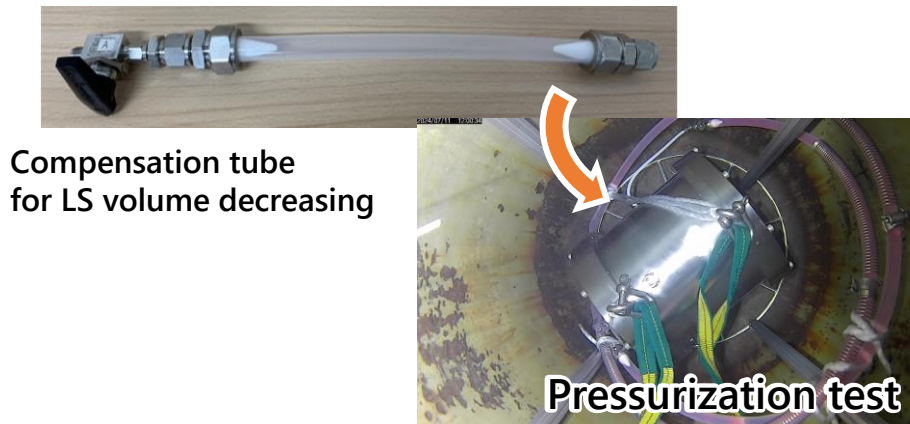
Original plan  
"Hanohano" (2005)



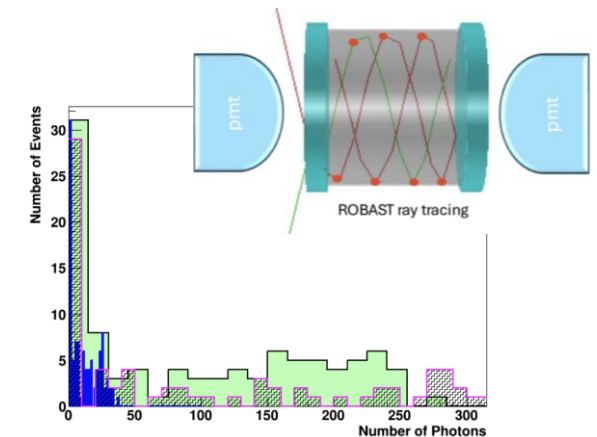
## Liquid scintillator R&D



## Pressure test for the component



## Photon simulation



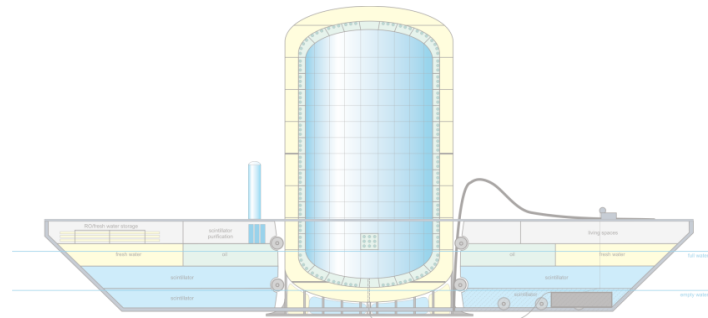
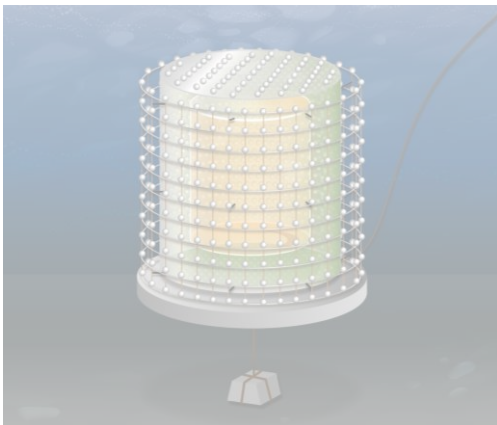


# Challenge for more precise Geo- $\nu$ observation

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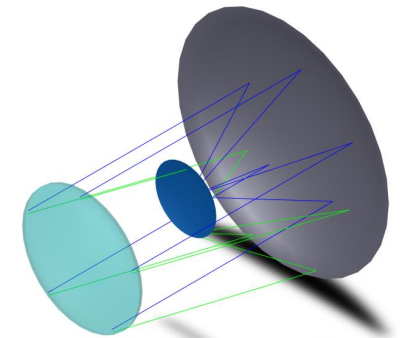
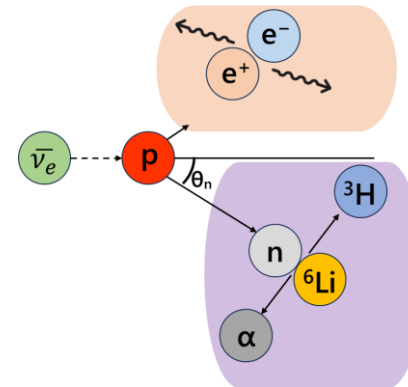
## Ocean bottom detector



- Reactor  $\nu$  identification
  - Reactor  $\nu$  and Geo- $\nu$  make same signal in liquid scintillator.
  - However, arrival direction is different.



## $\bar{\nu}_e$ direction detection with imaging (imaging detector)



# Concept of imaging detector

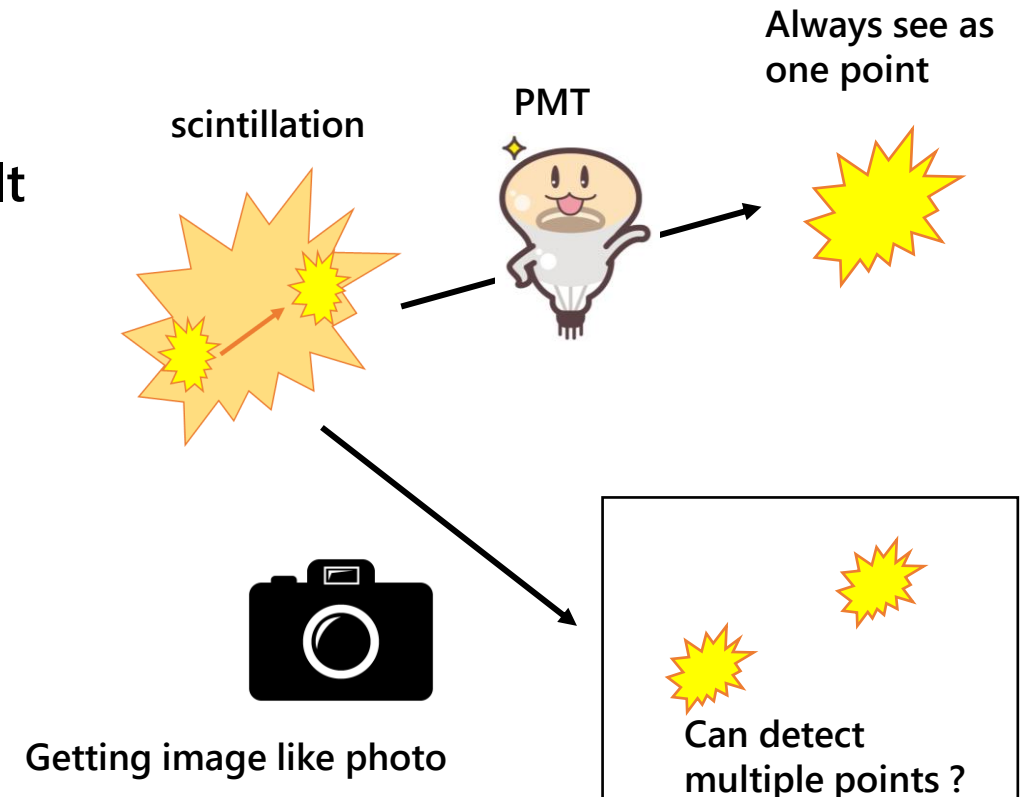
## - Camera-like detector to image scintillation directly

### Current KamLAND (by PMT) detection

- Event vertex is reconstructed from the time difference between photons being detected by each PMT.
  - Vertex resolution :  $\frac{13.7}{\sqrt{E [\text{MeV}]}} [\text{cm}]$
- Assuming scintillation occurs at one point
  - Detecting microstructure of scintillation is difficult



By imaging scintillation directly,  
imaging detector may improve vertex resolution  
and detecting microstructure of scintillation



# $\bar{\nu}_e$ direction detection with imaging scintillation

## - Improved vertex resolution through imaging enables $\bar{\nu}_e$ direction detection

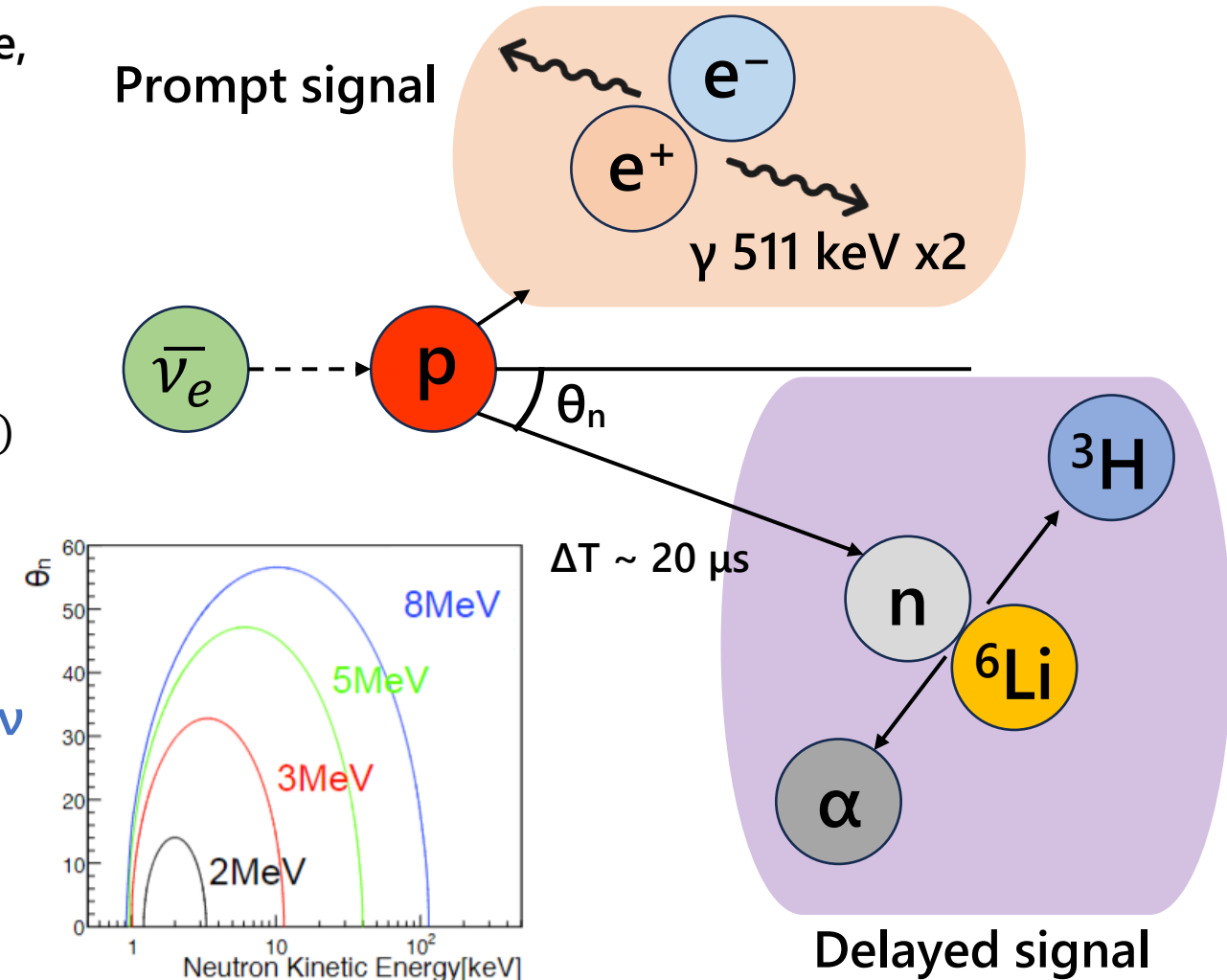
### Principle of direction detection

- If cross section for neutron capture becomes large, capture time becomes shorter. (e.g.  ${}^6\text{Li}$ -doped LS)
- Neutron conserves initial  $\bar{\nu}$ 's momentum, so initial  $\bar{\nu}$ 's direction can be regarded as the direction connecting prompt signal's and delayed signal's vertex.
- However, it needs more vertex resolution.  $O(1\text{ cm})$



Imaging improves the vertex resolution.  
Becoming distinguishable Reactor  $\bar{\nu}$  and Geo- $\bar{\nu}$   
Keeping research

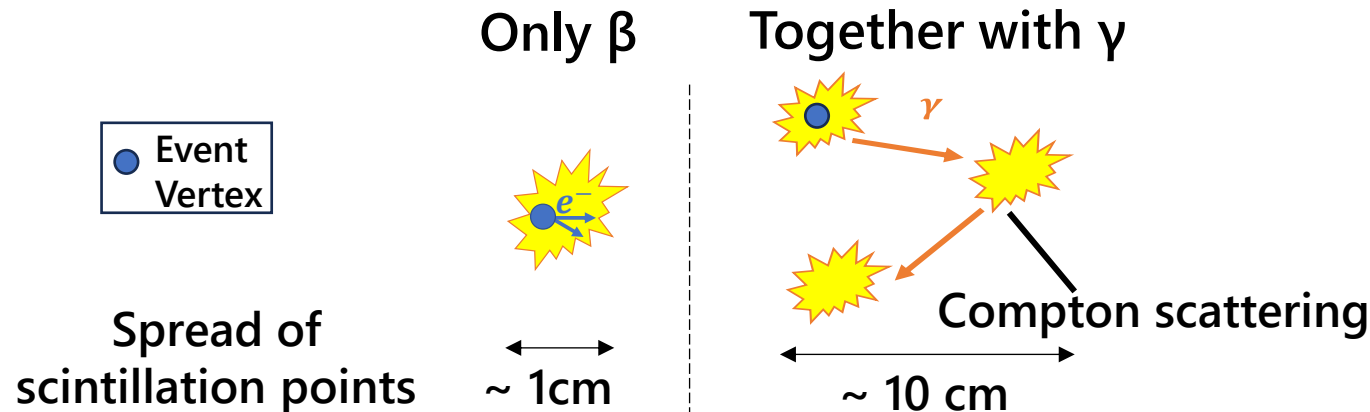
### Inverse $\beta$ decay in ${}^6\text{Li}$ -doped liquid scintillator



# Another application of imaging detector

- Imaging technics also can be applied to particle identification.

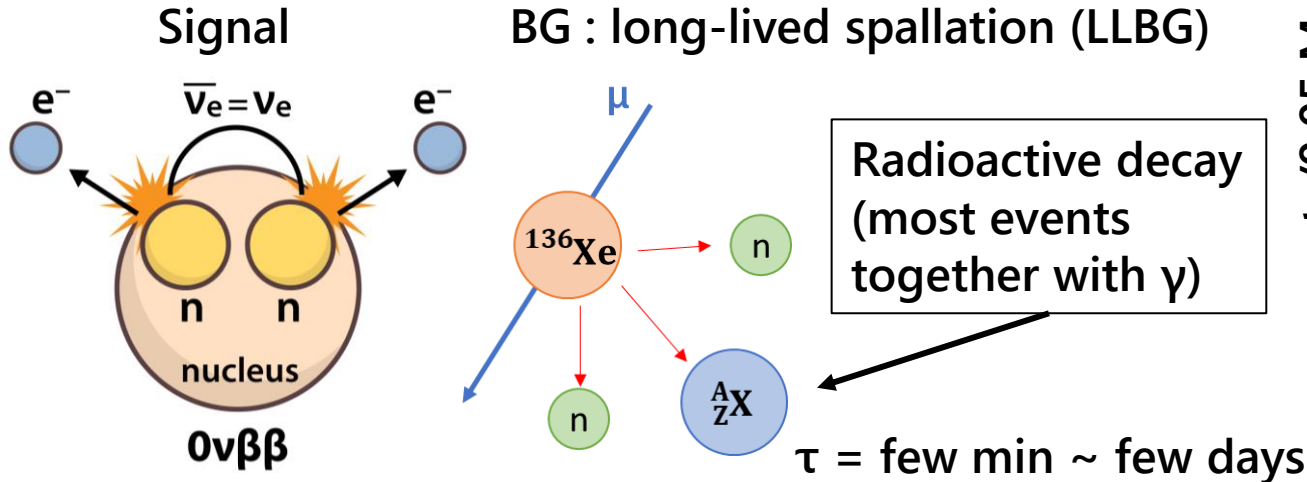
## Difference of scintillation



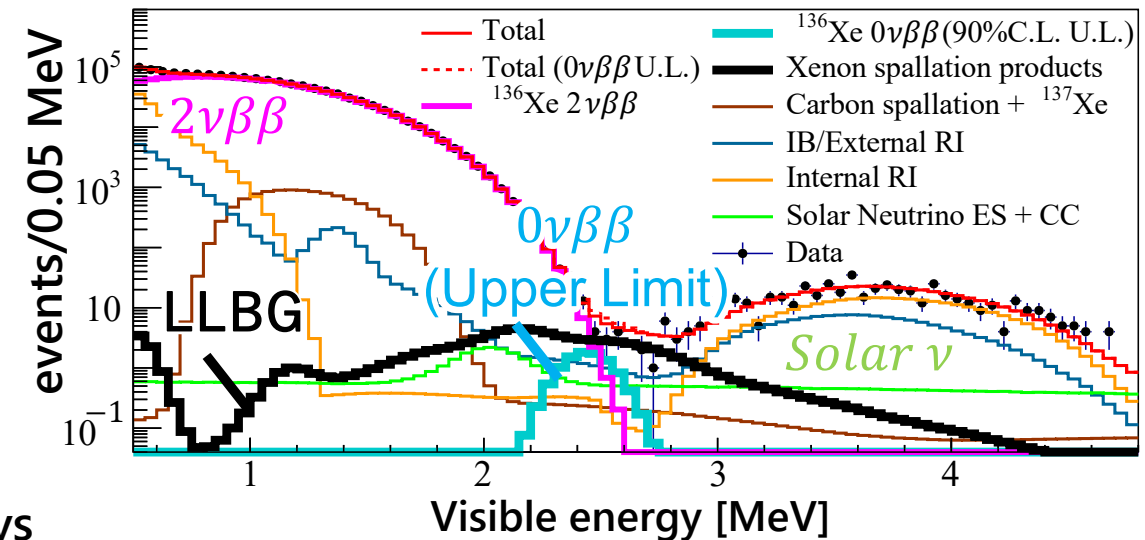
By capturing the spread of the emission,  $\beta$  and  $\gamma$  may be distinguishable.

## Application

## BG reduction for $0\nu\beta\beta$ observation

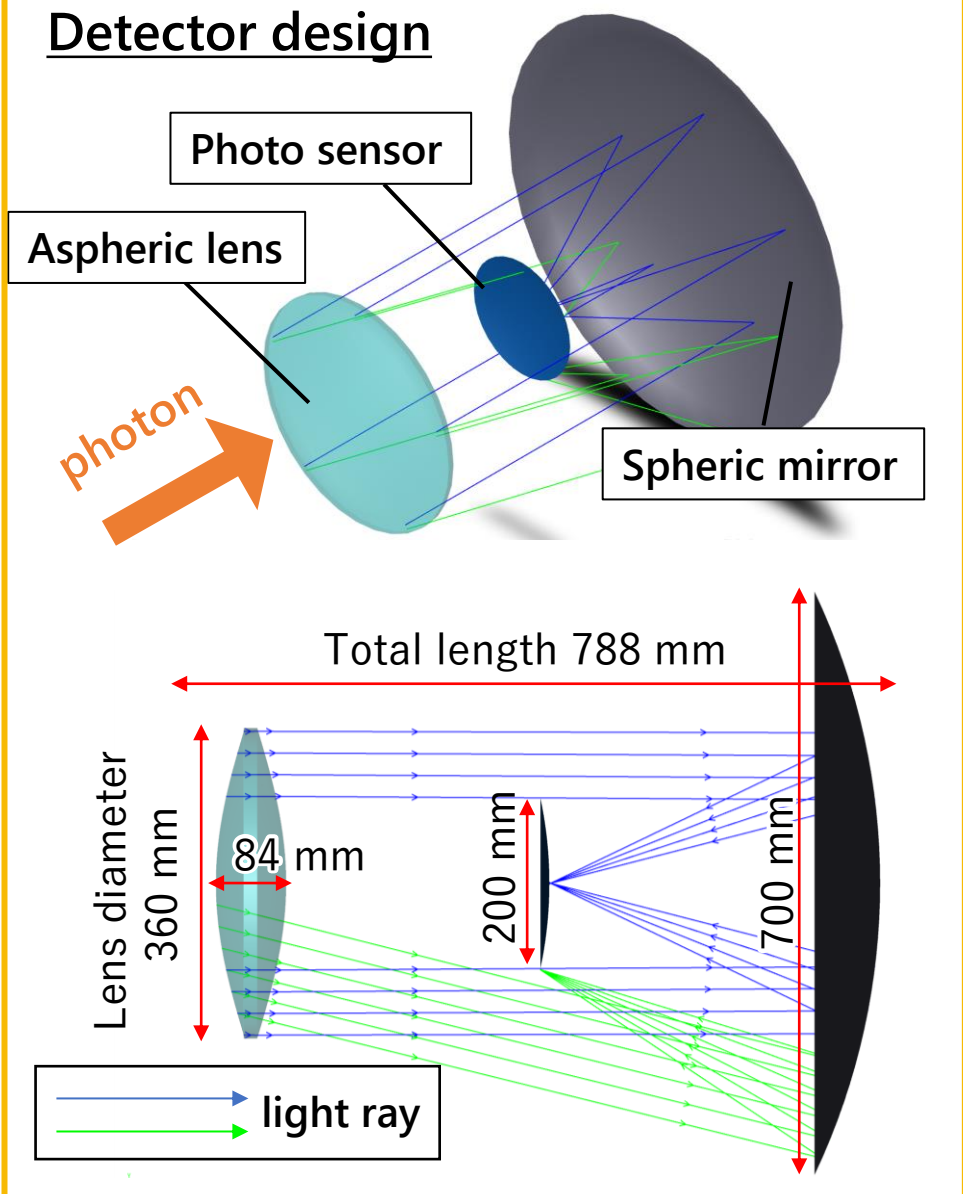


## Energy spectrum of KamLAND-Zen

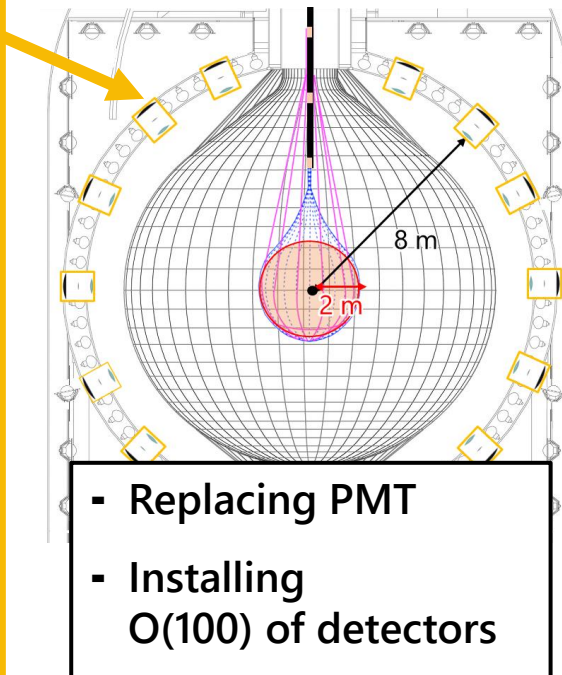


# Current progress

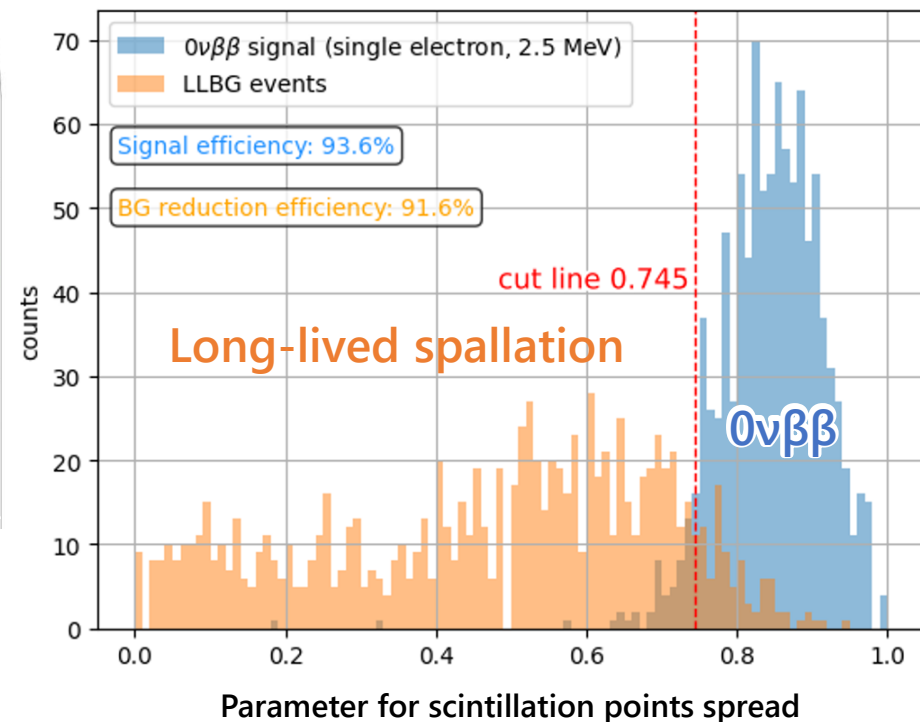
## Detector design



## Setting image



## Performance estimation (simulation)



- The design for using KamLAND2 has been created.
  - KamLAND2 : Upgraded KamLAND detector, Now being prepared
- Simulation shows this design can reduce long-lived spallation more than 90%.

# Summary

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## Geo- $\nu$ observation in KamLAND

- KamLAND realized Geo- $\nu$  observation with ultra-low background.
- We measured  $\nu$  flux from U & Th, and constrained their contribution and the amount of radiogenic heat.
- Now, full data analysis with machine learning is ongoing.

## Ocean bottom detector

- Ocean bottom is suitable site to observe Mantle Geo- $\nu$ .
- "OBD" is liquid scintillator detector plan for  $\nu$  observation in deep sea.
- Now, R&D phase. Property of prototype components are being researched.

## Imaging detector

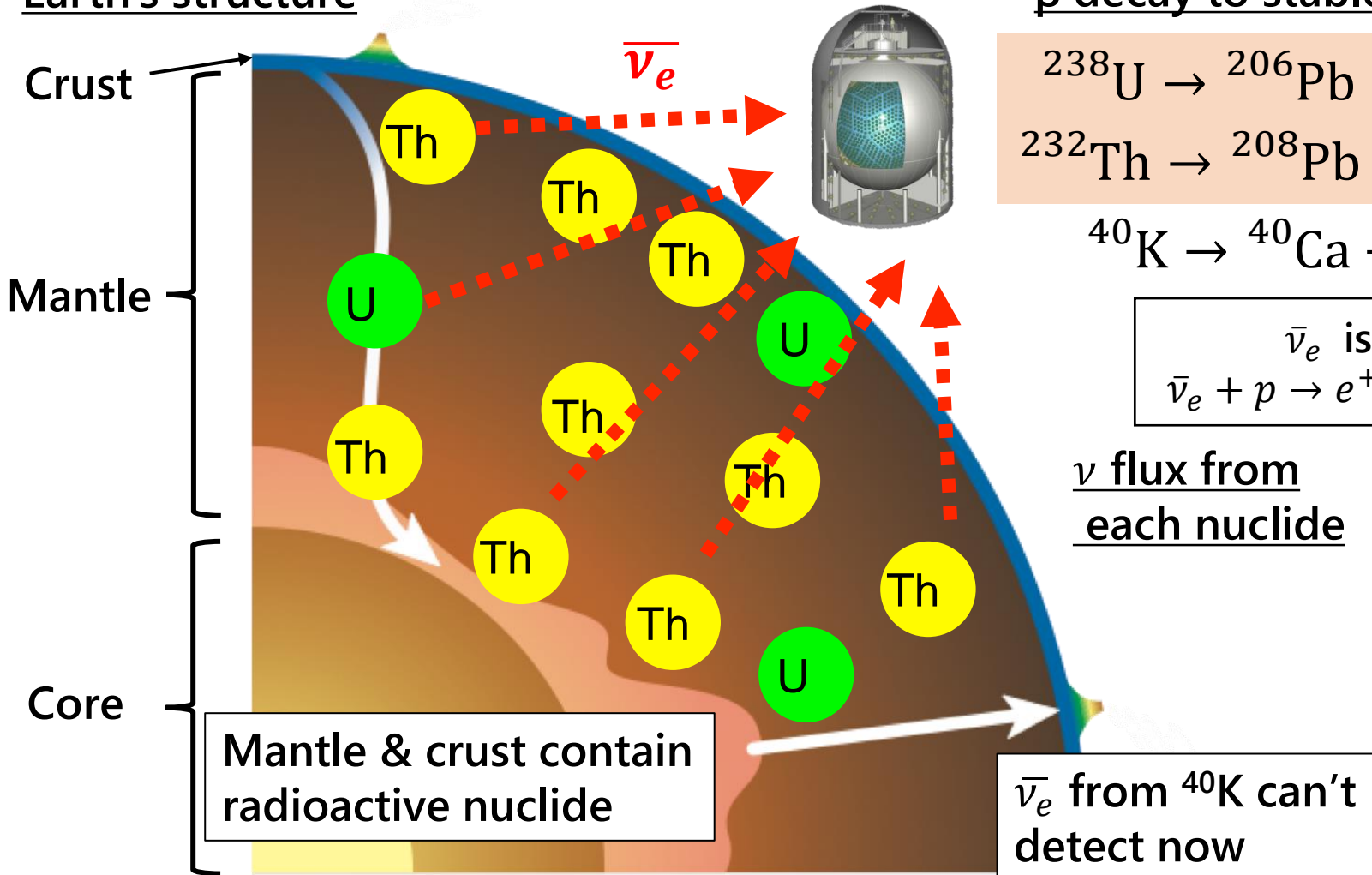
- It is camera-like detector to image scintillation directly to improve vertex resolution and capture scintillation structure.
- Using with LS which has short neutron capture time, it enables  $\nu$  direction detection.
- Now, it designs for BG reduction of  $0\nu\beta\beta$  observation by detecting the difference of scintillation spread.

# Back Up

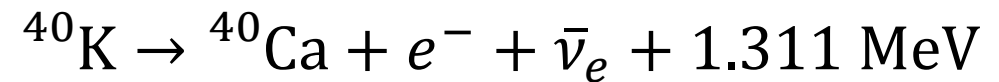
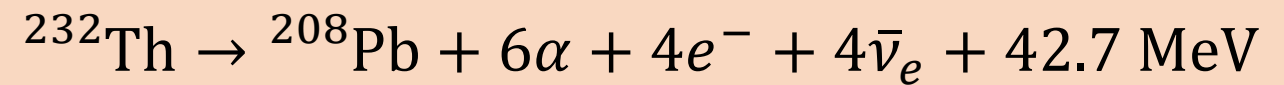
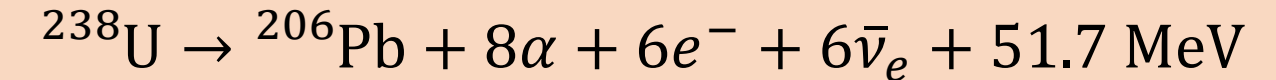
# What's Geo-neutrino ?

- $\bar{\nu}_e$  from  $\beta$  decay of isotopes inner Earth

## Earth's structure

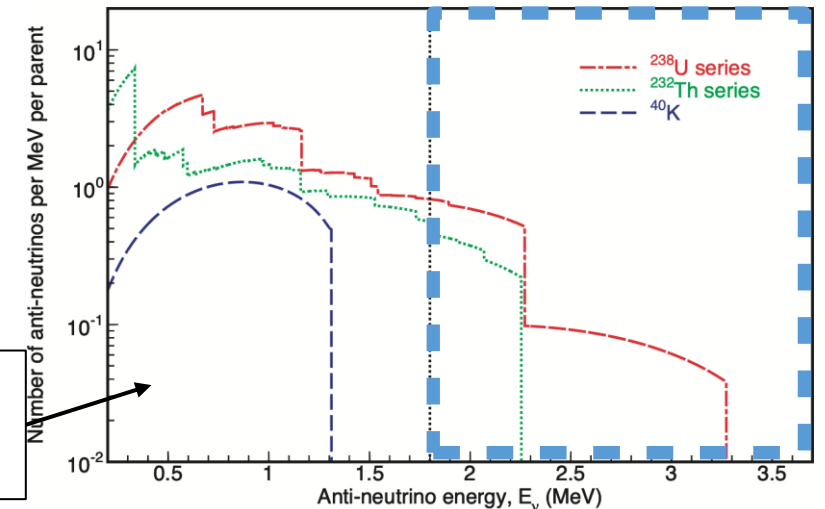


## $\beta$ decay to stable nuclide (Representative isotope)



$\bar{\nu}_e$  is observed by inverse  $\beta$  decay  
 $\bar{\nu}_e + p \rightarrow e^+ + n$  Energy threshold : 1.806 MeV

## $\nu$ flux from each nuclide





# Merit of Geo-neutrino observation

- Geo-ν can directly measure the amount of Earth's engine power source.

## Surface heat flow

**$46 \pm 3$  TW**

But we don't know  
the ratio of source...  
There're 3 models.

Heat source

### Radiogenic heat

Energy from radioactive decay  
Proportional to U & Th



### Primordial heat

The residual heat  
from Earth's formation

The heat drives mantle convection  
→ Important for Earth's dynamics

## Total radiogenic heat prediction (Continental Crust + Mantle)

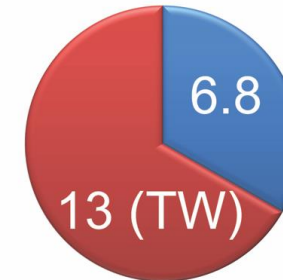
### Low Q



**10 TW**

Continental crust

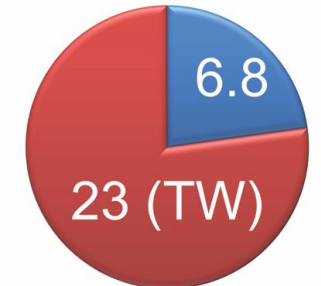
### Middle Q



**20 TW**

Mantle

### High Q



**30 TW**

Q : How much radioactive nuclides are left in mantle?  
→ Geo ν can measure its amount directly !